Supplementary material

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WIKIMEDIA	File:201405 liver.png
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(2) Supplementary contents

Image preprocessing

As shown in Supplementary Figure 4, all US images were preprocessed to remove any image regions outside of the actual scan area and to also detect and split images depicting dual US beams. The liver ultrasound image preprocessing pipeline includes 3 steps: image deidentification, background removal, and dual image detection. In the first step, ultrasound images were converted from the DICOM files to PNG files and cropped slightly, to remove protected health information in the DICOM headers and on the boundary of the images. Then in the second step, the most frequent pixel intensity value less than 50 was calculated to identify the background for each ultrasound image, which was then removed. To further crop out the background, for each image after filtering, the largest connected component (LCC) was calculated, and the image was cropped by the smallest square which can hold the LCC. By the end of this step, only the area within the ultrasound region was kept for each image. It is common to see that two ultrasound beams are combined in one saved image, so in the third step, we detect whether dual beams exist in one file. The image was first filtered by the Canny edge filter^[1], so only edges were kept, and then a Hough filter^[2] was applied to detect the top 8 line segments in the edge map in order to find the borders of the US beams. The intersections between the lines were then calculated, and if an intersection was found that lied near the horizontal center of the image, the image was considered a dual-beam image. This process can be somewhat noisy. However, in a US study there are typically many images of the same type. Therefore, we perform dual-beam detection for each image individually, then we aggregate the results across all images in a study using majority voting. If the majority of images were found to have a dual beam, we split all images in the study using the average intersection location. In Figure 5, an example of a dual-image file is presented, and the intersection point (yellow point in Step 3.b) was used to split the image. For all evaluation datasets, *i.e.*, HP-U, TM, and HP-T datasets, all images were manually verified as being preprocessed correctly.

Image selection

We are interested in investigating performance and reliability across viewpoints. Thus, for all our datasets, we only included US images from the viewpoints shown in Figure 1, which can be labelled as a. left lobe longitudinal, b. left lobe transverse, c. right lobe intercostal, d. lower right lobe intercostal (depicting liver/kidney contrast), e. subcostal depicting liver/kidney contrast, and f. subcostal with hepatic veins views. For the prospective TM dataset, we aimed to acquire two US images for each of the six viewpoints of Figure 1, except for the right lobe intercostal viewpoint, where we aimed to acquire four. Occasionally conditions did not allow us to collect certain viewpoints. For HP-U, and HP-T, we only included studies that had >=10 images of any of the studied viewpoints. As shown in Figure 1, we categorized these six viewpoints into four *view groups*: left liver lobe (LLL), liver/kidney contrast (LKC), and subcostal (SC).

Categorizing the view for each image is not necessary for the developmental datasets (BD-L and BD-V), as the DL algorithm just trains on each image independently without considering the view. However, even though the specific view for each image need not be categorized, ideally the training set only includes images from the four view groups. Because the BD-L and BD-V big-data datasets were extracted directly from the CGMH PACS, their US studies may contain images unsuited for liver steatosis analysis, e.g., images of organs other than the liver, liver viewpoints other than those of Figure 1, poor quality images, and even non-US images. So that these nonqualifying images did not impact the training of our DL model, we applied an additional filtering step to remove as many of these images as possible. Given the scale of data, it was not feasible to perform this filtering manually. Instead, we performed this semi-automatically by training a binary DL classifier, using the PyTorch library with hyper-parameters listed in Supplementary Table 4. We first randomly selected 44 US studies (696 images) from BD-L, and manually identified the corresponding US images as "qualifying", i.e., belonging to one of the liver viewpoints of Figure 1, or "non-qualifying". We also supplemented the positive training examples using the images within the HP-U and TM datasets. We then measured the sensitivity and specificity of the

trained binary classifier using a mini-validation dataset of 175 images from BD-L and chose the operating point corresponding to 95% specificity. Note, this filtering process was only used to clean the big-data cohorts and was not used for any of the evaluation datasets.

Training Steatosis Assessment DL Algorithm

Using the images from BD-L, we trained a DL classifier using the 2D US diagnoses extracted from the CGMH records. We opted for the ResNet family of DL classifiers^[3] given their ubiquity and performance in both natural imaging and medical imaging tasks. The ResNet family of DL classifiers are 2D convolutional neural networks^[4] that use the concept of residual connections to reduce the problem of vanishing gradients and improves learning speed. Based on performance on the BD-V validation dataset, we determined that the ResNet-18 variant performed best. The ResNet-18 has the added virtue of being lightweight, reducing overfitting tendencies compared to alternative variants. The US diagnoses are ordinal labels ranging from 0 to 3 corresponding to None; Mild; Moderate; and Severile steatosis Consequently, the learning task is an ordinal regression problem. We treat each image independently in training and follow the well-known binary decomposition approach to ordinal classification of Frank and Hall^[6]. As shown in Figure 2, instead of directly regressing the images to a numeric scale or training a four-class classifier, we decompose the problem into three binary classification tasks: estimating the probability the image represents >= mild, >= moderate, or = severe steatosis. Practically, this means that a three-output classification head is used on top of the ResNet-18 backbone. Under this scheme, the scalar labels for None, Mild, Moderate and Severe would be, respectively, converted to (0,0,0), (1,0,0), (1,1,0), and (1,1,1) multi-label vectors. Training is then conducted using standard cross-entropy loss. After training, a simple transformation produces a *continuous* score^[7] for each image that ranges from 0 to 1, with higher scores corresponding to more severe steatosis. For a single image, if the model confidences in the Frank and Hall labels are denoted \hat{y}_i , where *i* indexes whether the label is for >=mild,

>=moderate, or =severe, then the following formulation produces a severity assessment $\in [0,1]$:

$$\hat{p} = \sum_{i} \hat{y}/3.0,$$

where \hat{p} represents the image-wise confidence. As Figure 2 indicates, during inference, after feeding the model individual images to obtain image-wise scores, we then take the mean of image-wise scores across each view group to produce a single score for each view group. Additionally, we can also produce an "All View Groups" score, which is the mean score across all view groups in the study.

The hyper-parameters were selected to optimize our algorithm's performance on BD-V. We use an ImageNet pretrained network^[8], as that performed better than random initialization. The stopping criterion was the model checkpoint that performed best on BD-V, based on a rolling average of five epochs. Including the convolutional neural network architecture and model optimizer, other hyper- parameters that we tuned include initial learning rate, L2 regularization weight, image size and batch size. The details of these hyper-parameters are specified in Supplementary Table 5. We also applied an aggressive augmentation scheme to increase the variability in the image distribution presented to the network. These include additive Gaussian noise, brightness and contrast jittering, and random rotations. Each augmentation was applied on-the-fly to an image with a 50% probability. We also executed an aggressive cropping augmentation. Finally, all images were resampled to 256x256 pixels before being inputted into the deep neural network.

More Details on the Reliability Study

Repeatability Study (Experiment 1)

We used *TM* and *HP-U* to assess how many images are needed per view group to achieve repeatability. Note, for the *TM* dataset we randomly selected

only one US study for each patient to avoid sampling the same patient more than once. Typically, to calculate repeatability one simply acquires repeated measurements and performs an accepted repeatability metric. However, in our case each measurement can itself consist of the mean measurement across several image-wise scores. For example, if we are interested in the repeatability when averaging the score across three images to calculate a view group score, then two view-group measurements would require acquiring six images. This is an onerous data collection requirement. Instead of doing this, we simply first calculate the within-subject standard deviation, *s*, of the image-wise scores. We do this for each US study, which gives us a set of *s* values across different mean severity measurements. If we are then taking the mean across *k* images to obtain a view-group score, the resulting

within-subject standard deviation is simply $\sqrt{1/k} \times \overline{s}$. Finally, the withinsubject standard deviation of differences between repeated measurements can be estimated as $s_k = \sqrt{2/k} \times s$. The advantage of such an approach is that the within-subject standard deviation can be calculated for

any k without requiring the collection of more images.

As advocated by Bland and Altman^[9,10], these within subject standard deviations were then graphed across different view-group steatosis scores. Typically the repeatability coefficient (RC) could then be calculated using a mean s_k value across all US studies^[10]: the difference between two repeated measurements should be within the RC value for 95% of the US studies. However, because s_k is not uniform (typically greater variability at moderate steatosis levels), a uniform RC is not appropriate^[10]. Instead, we modelled the heteroskedasticity by regressing the within-subject standard deviation on mean severity scores^[10,11] using a cubic regression. We chose a cubic regression because there is a skew in the distribution of s_k values (see Supplementary Figure 1). We then used the worst-case RC value (max RC) as

a summary statistic, with 95% confidence intervals computed using percentile bootstrap (1000 bootstrap samples)^[12]. We conducted this for $k = \{1,2,3,4\}$ and for every view group.

Cross-Scanner Agreement (Experiment 2)

We evaluated agreement across scanners using the *TM* dataset, which consists of multiple studies taken on the same day of the same patient. A Bland-Altman analysis^[9,10] was performed for assessing cross-scanner agreement. This was simpler than what was done for repeatability, since for a chosen view group we just computed the mean score across all available images in a study. However, based on the repeatability measurements of Experiment 1, we only included view group scores with >=3 images. Thus, for two studies of the same patient across two different scanners, there are only two observations to compare. We calculated the bias and LOAs, where the latter are the limits by which 95% of the disagreements fall under^[10]. To deal with the same heteroskedasticity faced by the repeatability experiment, we regressed non-uniform limits of agreement (LOAs)^[10] and used the maximum upper LOAs and minimum lower LOAs as summary statistics. 95% confidence intervals were computed using the same bootstrap approach as in Experiment 1.

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(3) Supplementary Tables

Supplementary Table 1a Demographic Features of Each Cohort

		BD-L	BD-V	TM	HP-U	HP-T
Number	of	2899	411	246	147	112
Patients						
Number	of	17149	2364	733	147	112
Studies						
Number of Imag	ges	200654	27421	9215	1647	1996
Mean Age at Sca	an	56.5	56.9	56.6	49.1	50.0
Male, n (%)		1752	248	157	93	66
		(60.4)	(60.3)	(63.8)	(63.3)	(58.9)
Female, n (%)		1147	163	89	54	46
		(39.6)	(39.7)	(36.2)	(36.7)	(41.1)
NBNC, n (%)		353	51	56	103	63
		(12.2)	(12.4)	(22.8)	(70.1)	(56.2)
HBV, n (%)		1050	145	125	35	46
		(36.2)	(35.3)	(50.8)	(23.8)	(41.1)
HCV, n (%)		1322	190	65	9 (6.1)	3 (2.7)
		(45.6)	(46.2)	(26.4)		
Others/Unknow	vn,	174 (6.0)	25 (6.1)	0 (0.0)	0 (0.0)	0 (0.0)
n (%)						
Steatosis Grade	•					
US grade 0, n (%	6)	2529	352	N/A	N/A	N/A
		(87.2)	(85.6)			
US grade 1, n (%	6)	314	50	N/A	N/A	N/A
		(10.8)	(12.2)			
US grade 2, n (%	6)	50 (1.7)	8 (1.9)	N/A	N/A	N/A

US grade 3, n (%) 6 (0.3) 1 (0.3) N/A N/A N/A

Supplementary Table 1b. Additional Clinicopathologic Features of *HP-U* and *HP-T*

		HP-U			HP-T	
	NBNC	HBV	HCV	NBNC	HBV	HCV
Number of	103	35	9	63	46	3
Patients						
Mean Age at	47.5	51.8	56.6	48.8	52.2	43.2
Scan						
Male, n (%)	71	18	4	28	36	2
	(68.9)	(51.4)	(44.4)	(44.4)	(78.3)	(66.7)
Female, n (%)	32	17	5	35	10	1
	(31.1)	(48.6)	(55.6)	(55.6)	(21.7)	(33.3)
Mean BMI	27.5	25.4	27.1	25.7	25.8	27.5
Mean AST	64.9	64.1	58.0	115.4	87.0	71.7
U/L						
Mean ALT	110.2	92.7	76.4	213.4	151.8	128.0
U/L						
Mean PLT	246.9	201.4	207.3	248.8	186.2	179.7
10 ³ /mm ³						
Steatosis						
Grade						
grade 0, n (%)	10 (9.7)	11	3	22	21	1
		(31.4)	(33.3)	(34.9)	(45.7)	(33.3)
grade 1, n (%)	18	14	4	13	15	1
	(17.5)	(40.0)	(44.4)	(20.6)	(32.6)	(33.3)

grade 2, n (%)	31	4	0 (0.0)	6 (9.6)	8	0
	(30.1)	(11.4)			(17.4)	(0.0)
grade 3, n (%)	44	6	2	22	2 (4.3)	1
	(42.7)	(17.1)	(22.2)	(34.9)		(33.3)

Abbreviation: BD-L (big data learning group); BD-V (Big data validation group); HP-U (Histopathology Unblinded Test Group); TM (trimachine group); HP-T (Histopathology blinded Test Group); *AST* (aspartate aminotransferase); *ALT* (alanine aminotransferase); *HBV* (hepatitis B); *HCV* (hepatitis C); *NBNB* (non-HBV, non-HCV and excluded other liver diseases, E.g. alcoholic, autoimmune, etc); *PLT* (platelet)

Supplementary Table 2 Scanner brands, number of studies, and time ranges (if information is available in de-identified DICOM headers)

	BD-L, BD-V		НР-И		HP-T	
Scanner Brand	St	Time	St	Time	St	Time
	ud	Range	ud	Range	ud	Range
	ies		ies		ies	
ATL: HDI 5000	28	1/3/2011				3/18/201
	20	1/ 5/ 2011 -			16	1 -
	65	4/13/2015				9/2/2014
GE Healthcare:		11/11/201				
LOGIQ E9		4-				
	2	11/14/201				
		4				
GE Healthcare:	10	8/29/2012				
LOGIQ S8	19	- 9/5/2012				
Aloka Medical,Ltd.:	42	1/3/2011 -			r	5/2/2012
SSD 5500	73	10/17/201			۷	-

		4				3/19/201
						3
Hitachi Medical		8/27/2012				
Corporation: HI	16	-				
VISION Avius		8/31/2012				
Hitachi Medical		7/18/2012				
Corporation: HI	20	-				
VISION Preirus		9/25/2018				
Philips Medical		11/21/201				
Systems: EPIQ 7G	2	4 –				
		7/24/2018				
Philips Medical		11/17/201				
Systems: HD15	1	4 –				
	т	11/20/201				
		4				
Philips Medical				11/27/201		9/9/2011
Systems: iU22	88	1/3/2011 -	7	4 _	12	-
	27	9/28/2018		6/19/2019		9/4/202
				, ,		0
Siemens: S2000				7/12/2012		8/14/201
	19	1/6/2011 -	11	_	78	2 -
	3	9/28/2018	7	9/26/2019		1/29/202
						1
SuperSonic		5/14/2012				
Imagine SA:	72	-				
Aixplorer		7/24/2012				
Toshiba MEC US:	31	11/20/201		7/14/2015		6/9/2020
TUS-A300	45	4 -	23	-	4	-
		9/28/2018		7/2/2019		12/16/20

					20
Toshiba	MEC:		8/24/2012		
Xario		26	-	 	
			8/31/2012		
Unknown *		40	1/4/2011-		
		49	9/28/2018	 	

* Unknown: Toshiba SSA-370A or Toshiba SSA-700A, the exact model used was not recorded.

Supplementary Table 3 Performance Statistics for All Experiments Described in This Article. All experiments evaluated the same model, trained on the *BD-L* dataset.

ID	Experiment description	Result statistics
1	Estimate repeatability across view groups and different numbers of images per view group using two <i>TM</i> and <i>HP-U</i> cohorts	Max repeatability coefficient (RC), RC graphs
2	Estimate consistency across scanners and view groups using <i>TM</i> cohort	Bias, upper and lower limits of agreement, Bland-Altman graphs, % Agreement
3a	Estimate diagnostic performance across views using histology proven cohort <i>HP-U</i>	AUCROC (fatty % >=5%; >=33%; and >=66%), ROC Curves, Accuracy
3b	Compare diagnostic performance of DL model to FibroScan using studies with associated FibroScan scores from the <i>HP-U</i> cohort	AUCROC (fatty % >=5%; >=33%; and >=66%), ROC curves, Accuracy
4a	Estimate diagnostic performance across views using histology proven cohort <i>HP-T</i>	AUCROC (fatty % >=5%; >=33%; and >=66%), ROC curves, Accuracy

Abbreviation: BD-L (big data learning group); BD-V (Big data validation group); HP-U (Histopathology Unblinded Test Group); TM (trimachine group); HP-T (Histopathology blinded Test Group).

Supplementary Table 4 Description and values of all hyperparameters and properties of the image quality binary classifier. This deep learning (DL) model was used to automatically filter out non-qualifying images from the *BD-L* and *BD-V* dataset.

Hyperparameter	Description	Value
Network	Deep neural network layout	ResNet-18
architecture		
Image size	Size of image as the network input (in pixel)	256×256
Maximum	Maximum number each image is shown to	100
Epochs	the network during training	
Graphics	Graphics processing unit hardware	NVIDIA
Processing Unit		Titan V
Initial Learning	Network learning rate during training	0.0001
Rate		
L2	Weight decay (L2 penalty)	0.0005
Regularization		
Batch Size	Number of images processed in parallel	16
Solver	Optimizer to update weights and biases	SGD
L2 Regularization Batch Size Solver	Weight decay (L2 penalty) Number of images processed in parallel Optimizer to update weights and biases	0.0005 16 SGD

Abbreviation: BD-L (big data learning group); BD-V (Big data validation group);

Supplementary Table 5 Description and values of all hyperparameters an	ıd
properties of the deep learning workflow for steatosis severity assessmen	ıt

Hyperparameter	Description	Value
Network	Deep neural network layout	ResNet-18
architecture		
Image size	Size of image as the network input (in pixel)	256×256
Maximum	Maximum number each image is shown to	120
Epochs	the network during training	
Optimization	Stochastic gradient descent	
Algorithm		
Graphics	Graphics processing unit hardware	NVIDIA
Processing Unit		Titan V
Initial Learning	Network learning rate during training	0.0005
Rate		
L2	Weight decay (L2 penalty)	0.0001
Regularization		
Batch Size	Number of images processed in parallel	32
Solver	Optimizer to update weights and biases	SGD
Gaussian Noise	Standard deviation upper bound	0.01
Color Jittering	Brightness/Contrast change upper bound	0.2
Rotation	Affine transformation rotation upper bound	10
		Degrees
Scaling	Affine transformation ratio bound	[0.9, 1,1]
Augmentation	The possibility to apply each augmentation	50%
Probability	technique to a single image	

View	1 Image	2 Images	3 Images	4 images
LLL	0.46 (0.42, 0.51)	0.33 (0.30, 0.36)	0.27 (0.24, 0.29)	0.23 (0.21, 0.26)
RLL	0.37 (0.34, 0.40)	0.26 (0.24, 0.28)	0.21 (0.20, 0.23)	0.18 (0.17, 0.20)
LKC	0.53 (0.47, 0.58)	0.37 (0.33, 0.41)	0.30 (0.27, 0.34)	0.26 (0.24, 0.29)
SC	0.46 (0.42, 0.50)	0.32 (0.30, 0.36)	0.27 (0.24, 0.29)	0.23 (0.21, 0.26)

Supplementary Table 6 The max repeatability coefficient (RC) is tabulated across different view groups for the *TM* and *HP-U* datasets. Parentheses enclose bootstrapped 95% confidence intervals

Abbreviation: LLL (left liver lobe); RLL (right liver lobe); LKC (liver/kidney contrast); SC (subcostal); HP-U (Histopathology Unblinded Test Group); TM (Trimachine Group)

Supplementary Table 7 Literature review of works applying deep learning techniques for assessing hepatic steatosis using 2D US images. To be included, the works must be using deep learning models and only the deep learning results are highlighted here.

Referen ce	Byra et al. ²²	Chen et al. ²⁰	Cao et al. ²¹	Han et al. ¹⁹	Gumm adi et al. ¹⁷	Byra et al. ¹⁴	Biswas et al. ¹⁵	Ours
Referen ce in Main Body	22	20	21	19	17	14	15	
Publicat ion Year	2021	2020	2020	2020	2020	2018	2018	
Evaluati on Studies (case/co ntrol)	135‡	41	240 (138/10 6)	204 (140/64)	Unclea r patient or study- wise split	55 (38/17)‡	63 (36/27) ‡	147+112
Training Studies	Leave-o ne-out cross validati on	164	?		Unclea r patient or study- wise split	Leave-o ne-out cross validati on	Ten-fold cross validation, unclear if split across patients	19,513
Etiology	NBNC	NBNC	NAFLD	NAFLD	NAFL D/NA	Severely obese	NAFLD	HBV/H CV/

					SH			NBNC
US Scanner	Siemens S3000	Teraso n M3000	Mindra y Resona 7	Siemens S2000	6 model s	GE	US Scanner	13 models (trainin g); 5 models (evaluat ion)
Image	Graysca	Graysc	Graysca	PE data	Graysc	Graysca	Cravecalo	Graysca
type	le	ale	le	KF data	ale	le	Grayscale	le
Evaluati on Images/ Case Total Evaluati	4	205	?	2040	~5	10	?	>= 10 1647+19
on Images	540	205	?	2040	70	5504	1	96
Total Training Images	Leave-o ne-out cross validati on	820	852		725	Leave-o ne-out cross validati on	Ten-fold cross validation, unclear if split across patients	228075
Area of interest	Croppe d 224x224 pixel	Manua 1 3.5*3.5 cm	Manual 224*224 pixels ROI	256 R signals	F Manua 1 Crop	434×636 pixel Image	Auto-crop ped 128*128 Image	Auto-cr opped 256*256 pixel

	image	ROI						Image
Gold Standar d	MRI PDFF	Histol ogy	2D-US	MRI PDFF	Histol ogy/M RI PDFF/ 2D-US & Patient Histor y	Histolog y	Normal control	Histolog y
View	RLL and LKC	RLL	All Views	RLL	Unspe cified	RLL/Ki dney	RLL	All Views
Machine Learnin g Model	ResNet- 50	VGG-1 6	Custom CNN	CNN	Unspe cified CNN	Pretrain ed Inceptio n-ResNe tv2 CNN+S VM	SVM/ELM / CNN	ResNet- 18
Results AUCR OC (mild)		0.71†	0.933*					0.85-0.9 5
AUCR OC (mode rate)		0.75†	0.692*					

AUCR							
OC		0.66+	0.058*				0.91-0.9
(severe		0.00	0.938				2
)							
	0.86-0.91				89%		
AUCK					Se. &		0.87-0.9
OC			0.98	0.98	0.98 95%	1.0	3
Binary					C		
					Sp.		

* Based on 2D-US diagnosis; † Separate data splits for each cut-off; ‡ Cross validated

Abbreviations: AUCROC: area under the curve of receiver operating characteristic; CNN: convolutional neural network; HBV: hepatitis virus B; HCV: hepatitis virus C; MRI PDFF magnetic resonance imaging derived proton density fat fraction; NBNC: non-hepatitis B/non-hepatitis C; RF: Radiofrequency; RLL: right liver lobe; LKC: liver kidney contrast; SVM: support vector machine



(4) Supplementary Figures

E

Supplementary Figure 1 Repeatability coefficient (RC) plot across different 2D US viewpoints. (A) to (E) represents LLL, RLL, LKC, SC, and "All View Groups" respectively. Repeatability is measured when taking the mean score across three images per view group. "All View Groups" represents the score after taking the mean each resulting viewpoint score to create one score for each study.

Abbreviation: LLL (left liver lobe); RLL (right liver lobe); LKC (liver/kidney contrast); SC (subcostal);



Supplementary Figure 2 ROC analysis of *HP-T* (Individual view group setting). (A) to (E) shows ROC curves of the deep learning (DL) model for diagnosing hepatic steatosis grades on HP-T with LLL, RLL, LKC, SC, and "All View Groups", respectively.

Abbreviation: HP-T (Histopathology blinded Test Group); LLL (left liver lobe); RLL (right liver lobe); LKC (liver/kidney contrast); SC (subcostal);



Supplementary Figure 3 ROC analysis of *HP-T* (Complete view group setting). (A) to (E) shows ROC curves of the deep learning (DL) model for diagnosing hepatic steatosis grades on HP-T with LLL, RLL, LKC, SC, and "All View Groups", respectively.

Abbreviation: HP-T (Histopathology blinded Test Group); LLL (left liver lobe); RLL (right liver lobe); LKC (liver/kidney contrast); SC (subcostal);



Supplementary Figure 4 Liver ultrasound image preprocessing pipeline includes 3 steps: image deidentification, background removal, and dual image detection. In "Step 3.b", the figure is showing the top 8 lines detected by the Hough transform (in blue, two lines are along the boundaries and might not be seen), and the detected intersection point (in yellow).