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Prospective Study

Robotic-assisted proctosigmoidectomy for Hirschsprung's disease: a multicenter prospective study

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Abstract

BACKGROUND

Robotic surgery is a cutting-edge minimally invasive technique that overcomes many shortcomings of laparoscopic techniques, yet few studies have evaluated the use of robotic surgery to treat Hirschsprung's disease (HSCR).

AIM

We aimed to analyze the feasibility and medium-term outcomes of robotic-assisted proctosigmoidectomy (RAPS) with sphincter- and nerve-sparing surgery (SNS) in HSCR patients.

METHODS

From July 2015 to January 2022, 156 rectosigmoid HSCR patients were enrolled in this multicenter prospective study. Their sphincters and nerves were spared by dissecting the rectum completely from the pelvic cavity outside the longitudinal muscle of the

rectum and then performing transanal Soave pull-through procedures. Surgical outcomes and continence function were analyzed.

RESULTS

No conversions or intraoperative complications occurred. The median age at surgery was 9.50 mo, and the length of the removed bowel was 15.50 ± 5.23 cm. The total operation time, console time and anal traction time were 155.22 ± 16.77 , 58.01 ± 7.71 and 45.28 ± 8.15 min. There were 25 complications within 30 days and 48 post-30-day complications. For children aged ≥ 4 years, the bowel function score (BFS) was 17.32 ± 2.63 , and 90.91% of patients showed moderate-to-good bowel function. The postoperative fecal continence (POFC) score was 10.95 ± 1.04 at 4 years of age, 11.48 ± 0.72 at 5 years of age, and 11.94 ± 0.81 at 6 years of age, showing a promising annual trend. There were no significant differences in postoperative complications, BFS, and POFC score related to an age at surgery of ≤ 3 mo or > 3 months.

CONCLUSION

RAPS is a safe and effective alternative for treating HSCR in children of all ages; it offers the advantage of further minimizing damage to sphincters and perirectal nerves and thus providing better continence function.

Key Words: Robotic-assisted; Hirschsprung's disease; Continence function; Sphincter; Nerve

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Core Tip: We present the largest series of patients with Hirschsprung's disease treated with robotic-assisted proctosigmoidectomy (RAPS). RAPS is a safe and effective

alternative for **treating** Hirschsprung's disease **in children** of all ages. It offers the advantage of further minimizing damage to sphincters and perirectal nerves and thus providing better **fecal** function.

INTRODUCTION

Although beneficial for children with Hirschsprung's disease (HSCR), laparoscopic operation is more challenging than open operation, especially in newborns and infants. To address the drawbacks of laparoscopic surgery, a robotic system may be considered. Robotic-assisted surgery is utilized in various areas due to its numerous advantages, particularly in complex operations, such as anorectal malformations and choledochal cysts in children ^[1,2] and prostate and rectal cancer in adults ^[3,4].

Recently, laparoscopic techniques have developed into an effective treatment for HSCR. As previously shown, these minimally invasive surgical techniques result in better early postoperative outcomes than the open procedure ^[5,6], and the long-term results are similar between laparoscopic and open procedures ^[7]. Nevertheless, laparoscopic surgery for HSCR is still considered to be one of the most difficult operations in anorectal surgery. With the introduction and application of robotic surgical platforms, this technology is gradually being adopted for the treatment of HSCR. However, the safety and efficacy of the technology in treating pediatric HSCR patients have been evaluated in only a few studies.

In this paper, we present our initial experience with robotic-assisted proctosigmoidectomy (RAPS) with sphincter- and nerve-sparing surgery (SNS) for treating HSCR. To our knowledge, this represents the largest series of SNS-RAPS in children reported to date. The SNS-RAPS procedure is thoroughly detailed.

MATERIALS AND METHODS

Study design

From July 2015 to January 2022, a multicenter prospective study of consecutive children with rectosigmoid HSCR who underwent uniform SNS-RAPS was carried out

at three centers (Union Hospital, Tongji Medical College, Huazhong University of Science and Technology; Guangzhou Women and Children's Medical Center, Guangzhou Medical University; Wuhan Children's Hospital, Tongji Medical College, Huazhong University of Science and Technology). A total of 156 patients were enrolled, and all operations were performed by experienced surgical teams from three centers. Since the time the da Vinci Surgical System Si (Intuitive Surgical, Sunnyvale, CA) was introduced at the three centers to treat HSCR, all HSCR cases have been recorded in a prospectively designed database. Patient demographics, surgical parameters, and postoperative data were recorded.

This study was approved by the ethics committee at each participating center and registered in the Chinese Clinical Trial Registry (Registration ID: ChiCTR2000035220). Written informed consent was obtained from the legal guardians of each patient. The study has been reported in accordance with the Declaration of Helsinki.

Patients

Patients diagnosed with rectosigmoid HSCR preoperatively were candidates for SNS-RAPS. The diagnosis was based on clinical symptoms and signs, barium enema results, rectal aspiration biopsy, anorectal manometry and intraoperative biopsy. Patients with trisomy 21, total colonic aganglionosis, long-segment HSCR, HSCR combined with preoperative enterostomy, and surgical contraindications were excluded. The patient selection process is detailed in Figure 1. All patients received a unified preoperative preparation and postoperative treatment plan at all centers.

Colonic irrigation with warm saline (100-200 mL/kg) was used to prepare the colon for 3-7 days. Metronidazole (25 mg/kg, bid) was given orally for 3 days (1-2 days for neonates) preoperatively, and one dose of cefoperazone was provided during anesthesia induction.

Operative procedure

Under general anesthesia, the patient was placed in the supine position, and three trocars were placed. The CO₂ insufflation pressure was set at 8-10 mmHg, and the flow rate at 2.5-4.5 L/min. The operation was performed using three ports, including a

straight-cut umbilical trocar accommodating a 12 mm 30° telescope and two working trocars with 8 mm robotic devices on either side (Figure 2). The robotic arms were oriented from the caudal direction. The aganglionic segment range was assessed by seromusculature biopsy using robotic monopolar scissors, and interrupted 5-0 sutures were placed in cases of bleeding or mucosal rupture. The needle and suction were alternately inserted for operation through the 8 mm port on one side, which required the process of removing and reinserting the operative instrument. A Maryland dissector and a robotic hook were used to perform the dissection. After creating a window on the sigmoid mesentery, we clipped and divided the sigmoid artery trunk and then mobilized the mesentery up to the level of the inferior mesenteric artery. SNS robotic endorectal dissection was performed circumferentially down to the pelvis, which was the most unique and crucial part of the operation. Dissection was begun circumferentially at 1.0 cm above the peritoneal reflection. The rectum was mobilized outside the longitudinal muscle layer (that is, under its serosa or proper rectal fascia extended serous layer below the peritoneal reflection), with the anatomical plane farther away from Denonvilliers' fascia and the nerve plexus anterior or lateral to the rectum. When we pulled the rectum cranially, intestinal wall muscle layers provided greater tensile strength than the mucosa, allowing the pelvis to be shallower (Figure 3) and avoiding intraoperative intestinal mucosal tearing with peritoneal contamination. Since the robotic platform allowed for dissection in a narrow field, we were able to dissect the rectum to a lower level, nearly up to the dentate line. The mobilization of the rectum reached 4-7 cm into the pelvis (Figure 4D).

After the robot was unlocked, a circular incision was made 0.5-1 cm from the dentate line (Figure 5C), dividing the mucosa upward by 0.2-0.4 cm, breaking through the muscular cuff and exposing the robotic dissection plane in the pelvis. The diseased colon was then gently pulled out through the anus. The posterior wall was partially resected in a V-shape, and the pointed end of the "V" reached the level of the dentate line to release internal anal sphincter achalasia. To avoid residual dysfunctional bowel, we uniformly excised the dilated and thickened bowel; we then performed Soave's

anastomosis with interrupted 5-0 or 4-0 absorbable sutures above the biopsy site. After the diseased bowel was removed, the specimen was measured for its overall length and the pelvic dissection length (Figure 5D).

Postoperative management

Intravenous antibiotics (cefoperazone, 50 mg/kg, bid) were given for the first 3 days, and a urinary catheter was left for 24-48 h after surgery. No nasogastric tube or drains were left in place, but a rectal tube was left for 5 days postoperatively to help the passage of intestinal contents and gas through the anus. Instead of sutures, we used butterfly shaped tape to fixate the tube and reduce postoperative discomfort. The patient was discharged after being confirmed to be clinically stable and tolerant of a full oral diet. A routine digital rectal examination was performed postoperatively at 2 wk, and an anal dilatation plan was formulated.

Postoperative variables and definitions

The bowel function score (BFS) was used to evaluate overall bowel function^[8], while the postoperative fecal continence (POFC) score focused on SNS-related incontinence^[9]. Children aged ≥ 4 years were assessed twice for each score as shown in Figure 6 and Figure 7. A $BFS \geq 17$ was represented as the lower limit of good/normal functional outcomes as more than 90% of people aged ≥ 4 years in the normal population met this criterion^[10]. Soiling referred to the actual presence of feces in the underwear without the patient's awareness, while fecal marks on the underwear was regarded as staining. We briefly defined the normal stool frequency as 1-3 times daily or once every 1-3 days. The diagnosis of HSCR-associated enterocolitis was based on the definitions by Teitelbaum and Coran^[11]. Post-30-day complications were defined as complications occurring 30 days to 1 year after surgery.

Statistical analysis

Categorical variables are presented as counts and percentages, while continuous variables are presented as the mean \pm standard deviation or median (range). The Kolmogorov-Smirnov test was used to assess the normality distribution of the data. To evaluate the differences between groups, the chi-square test or Fisher exact test was

used to analyze categorical variables, and the Mann-Whitney U test was used to compare continuous variables because the data did not meet the normal distribution criteria. IBM SPSS Statistics version 26.0 was used for statistical analysis. A P value of < 0.05 was considered indicative of statistical significance.

RESULTS

Patient demographics and operative data

A total of 184 participants were assessed for eligibility, and 156 patients were finally enrolled in this multicenter prospective study (Figure 1). The demographics and operative outcomes are shown in Table 1. No conversion or intraoperative complications occurred. The median age at surgery was 9.50 (range: 0.60-132.00) months, and the weight was 9.09±3.68 kg. The total operative time was 155.22±16.77 min, and the robotic console time was 58.01±7.71 min. The anal traction time was 45.28±8.15 min, which included 15.21±2.67 min for transanal dissection and 30.01±5.82 min for anastomosis. The length of the removed bowel was 15.50 ±5.23 cm, and the pelvic dissection depth under endoscopy was 4.50±0.47 cm. The intraoperative estimated blood loss was 5.01±1.81 ml.

Postoperative outcomes

Postoperative outcomes are detailed in Table 2. The hospital stay was 7.25±1.67 days, and the median follow-up duration was 44.00 (range: 6.00-78.00) months. Eight patients were lost to follow-up one year after surgery. Postoperative complications were assessed in accordance with the Classification of Surgical Complications ^[12]. The postoperative 30-day complications included Clavien–Dindo grade II complications in two patients with wound infections, two patients with lung infections, six patients with enterocolitis, and thirteen patients with perianal dermatitis, all of whom were corrected by conservative treatment. One patient exhibited a Clavien–Dindo grade IIIa complication (anastomotic leakage treated by resuturing with presacral drainage ^[13]), and one patient had a Clavien–Dindo grade IIIb complication (omental hernia requiring surgical correction). There was no uroschisis, urinary incontinence or cuff abscess. Post-

30-day complications included Clavien–Dindo grade I complications, namely, seven soilings (received bowel habit training) and eighteen stainings (no change of underwear required) as well as Clavien–Dindo grade II complications, namely, two cases of anastomotic strictures (underwent anal dilation treatment without anesthesia), sixteen cases of enterocolitis (received rectal decompression, irrigation and broad-spectrum antibiotics), four cases of constipation (received a laxative and enema) and one case of perianal dermatitis (received topical medication).

Normal stool frequency and enterocolitis at 1-6 years after surgery

As listed in Table 3, we divided follow-up into four phases: ≤ 1 year, $1 < \text{years} \leq 2$, $2 < \text{years} \leq 4$, and $4 < \text{years} \leq 6$, with further analysis of short- to medium-term stool frequency and enterocolitis. The incidence of normal stool frequency increased steadily while the enterocolitis rate decreased gradually over time; the overall normal stool frequency rate increased from 55.13% to 89.06% under diet control (younger group: 53.70% to 86.36%, older group: 55.88% to 90.48%) (Figure 8A) and the overall enterocolitis rate declined from 10.26% to 4.69% (younger group: 11.11% to 4.55%, older group: 9.8% to 4.76%) (Figure 8B).

BFS and POFC score in the assessment of medium-term functional outcome

The BFS and POFC score are shown in Table 4. Eighty-eight patients aged ≥ 4 years were evaluated with two scoring systems during follow-up. The bowel functional result was good ($\text{BFS} \geq 17$) in 66 patients (75.00%), moderate ($12 \leq \text{BFS} \leq 16$) in 14 patients (15.91%) and poor ($\text{BFS} < 12$) in 8 patients (9.09%). The total BFS was 17.32 ± 2.63 , with satisfactory scores for each item. The POFC score at 4, 5 and 6 years of age postoperatively demonstrated a promising trend annually, with values of 10.95 ± 1.04 , 11.48 ± 0.72 , and 11.94 ± 0.81 , respectively (Figure 8C).

Comparison of efficacy between patients aged ≤ 3 mo and aged > 3 mo at surgery

The outcomes of the group comparison are shown in Table 3, Table 5 and Table 6. Due to the small number of neonates in this series, we carried out a subgroup analysis to assess defecation function in younger infants, grouping the patients by age into ≤ 3 mo (younger group, $n = 54$) and > 3 mo (older group, $n = 102$). There was no significant

difference in postoperative complication rates, BFSs (younger group: 17.19 ± 2.87 , older group: 17.37 ± 2.54) or POFC scores at 4, 5 and 6 years of age postoperatively (younger group: 10.70 ± 0.99 , 11.38 ± 0.62 , 11.71 ± 0.76 ; older group: 11.07 ± 1.05 , 11.52 ± 0.76 , 12.00 ± 0.83) between the two groups (Figure 8C).

DISCUSSION

Robotic procedures are rapidly replacing open or laparoscopic procedures for the adult population in challenging procedures, such as operations for rectal and prostate cancer ^[3,4]. Nevertheless, the adoption of robots in pediatric surgery is low. Robotic surgery failed to show substantial benefits in studies comparing it to laparoscopic surgery because the procedures were initially used for less complex operations, such as the Nissen fundoplication ^[14]. In technically demanding situations, the application of robots for abdominal surgeries in children is relatively limited. Furthermore, only a few studies have revealed the feasibility of robotic-assisted surgery for HSCR, and the patient numbers were too small to generalize the application of robotic surgery in this field ^[15-18]. There is still a lack of studies involving large samples and long follow-up on functional outcomes. To our knowledge, 156 consecutive HSCR children who received RAPS represent the largest series in the literature. Long-segmental HSCR, total colonic aganglionosis and trisomy 21 have been demonstrated to negatively affect the prognosis of HSCR patients ^[19-21]. Aiming to focus on the effect of surgical techniques on the postoperative outcomes of HSCR, we excluded these influencing factors and performed RAPS only on children with rectosigmoid HSCR.

The core of the original Soave procedure is pelvic endorectal dissection under the mucosa, but the mucosa is easily ruptured, resulting in pelvic contamination or mucosal residue. This explains the high rate of muscular sleeve infection following surgery in that era ^[5]. Pelvic endorectal dissection is a determining step in minimally invasive surgery for HSCR. Laparoscopic surgery facilitates tissue dissection in narrow spaces, and the technique still follows the concept of the original Soave procedure for nerve sparing. However, stiff laparoscopic instruments and unstable vision make submucosal

rectal dissection more challenging, resulting in a higher mucosa rupture rate. Instead, extrarectal dissection is performed tightly around the rectal wall to 1-2 cm below the peritoneal reflection, and then a long-distance submucosal dissection is conducted through the anus as in Georgeson's technique [22]. For selected patients, a totally transanal endorectal technique with submucosal dissection can even be performed as in Torre's technique [23]. These procedures have been demonstrated to provide better short-term outcomes than open surgery, with similar long-term outcomes [7,24,25]. Nonetheless, some studies have found that minimally invasive surgery, particularly totally transanal surgery that requires more anal dissection, results in poorer long-term defecation function than open surgery, especially in neonates [8,26,27]. This is probably a result of the technique's increased risk of anal sphincter traction/injury [28]. Therefore, we hypothesized that RAPS could reduce these risks to support better long-term bowel function for patients.

Herein, the primary strength of our robotic-assisted technique is that a new endorectal dissection layer (outside the longitudinal muscle) can be established. This potential gap between anatomical structures exists objectively [29]. The new layer is farther away from the urinal nerves on both sides of the rectum and the sexual nerves ahead of the Denonvilliers' fascia [30]. A diagram of the pelvic dissection layer is shown in Figure 4. The robotic system provides a magnified 3D image, stable maneuverability and articulated movement in the narrow area *via* small incisions. Another major advantage is the image stability from robotic arm support as minor camera movements can cause image shifting. These merits facilitate ideal identification of the subserosa and precise rectum dissection, thus guaranteeing nerve-sparing. In addition, the rectum with intact longitudinal and circular muscles can be pulled strongly and is less prone to rupture; thus, the surgeon is able to pull the rectum cranially to make the pelvis shallower (Figure 3), allowing the dissection to nearly reach the dentate line (Figure 4D). Extensive intra-abdominal endorectal dissection would result in less need for transanal dissection and simpler transanal procedures, thus permitting minor or no sphincter damage. As our results show, the pelvic dissection could reach a depth of

4.50±0.47 cm, so the length of the rectum dissected transanally was greatly shortened to 0.20-0.40 cm (Figure 5D). This reduces the time and intensity of sphincter traction. As reported, prolonged transanal dissection is prone to sphincter traction/injury [19,31]. Hence, robotic practice in pelvic rectal dissection may offer an excellent surgical tool.

Due to the additional docking and setting time of the robotic arms, the total operation time of robotic procedures is generally longer than that of open or laparoscopic procedures [16,32]. In our series, however, the operative time was 155.22±16.77 min and was comparable to that of laparoscopic surgery, which varied from 94.00 to 294.00 min in previous large-sample studies [7,19,33-37]. Moreover, our results revealed that postoperative complication rates were similar or even lower than those of transanal or laparoscopic approaches [19,33-35]. There were no cuff abscesses in our series. This is related to precise and complete dissection of the rectum outside the longitudinal muscle up to the dentate line, preventing mucosal tube injury and ensuring no residual rectal mucosa. Previous studies have shown that the incidence of urinary incontinence in HSCR patients postoperatively ranges from 2.70-22.00% [38-42], and urine retention ranges from 1.04-6.67% [43-45]. Urinary complications following pelvic procedures may be caused by direct damage or indirect thermal radiation injury to the nerve endings controlling voiding. No uroschesis or urinary incontinence occurred after removal of the urinary catheter 24-48 h after surgery in any of the patients. This highlights the most obvious advantage of SNS-RAPS, which is the precise safeguarding of the urinal nerve around the rectum. Following this logic, good short-term bladder nerve protection after RAPS could indirectly predict better long-term defecation and sexual nerve function.

Postoperative bowel function and continence are the most important criteria for evaluating the effectiveness of SNS-RAPS. BFS was used for a comprehensive assessment of defecation, soiling, constipation, and social problems. Previous studies evaluating long-term outcomes (follow-up ranged from 9.5 to 28 years) after open, laparoscopic or transanal approaches have shown that 88.00% to 89.00% of HSCR patients obtained moderate-to-good bowel function (good: BFS≥17, 52.00-63.00%;

moderate: $12 \leq \text{BFS} \leq 16$, 26.00-36.00%) [8,46], with an overall score of 15.00 to 17.10 [8,10,19,46-48]. One clinical trial even found that neonates with HSCR achieved a BFS of 17.44 for short-segment HSCR and 19.06 for long-segment HSCR after a transanal procedure (follow-up for more than 8 years) [49]. Our medium-term findings showed an overall BFS of 17.32 ± 2.63 and that 90.91% of patients achieved moderate-to-good bowel function (good: 75.00%; moderate: 15.91%), which was comparable to or better than the long-term results of previous studies. As studies have shown, postoperative bowel function improves with age [9,47], so we predict that our series of patients will have better long-term bowel function. Furthermore, we used the POFC score to analyze fecal incontinence, reflecting the role of SNS-RAPS in nerve and sphincter protection [9]. The total POFC score gradually improved and was satisfactory in patients at 4, 5 and 6 years of age following surgery (10.95 ± 1.04 , 11.48 ± 0.72 and 11.94 ± 0.81), representing a result similar to or superior to that of laparoscopic operation (8.60-11.30) [9,50]. Postoperative functional results are strongly related to long-term quality of life (QoL) [10,47,48]. Satisfactory BFS and POFC scores in this series suggested that patients will achieve good long-term QoL.

Researchers in previous studies have mixed opinions on the efficacy in younger infants, especially neonates, compared with that in older children [50,51]. Although its appropriateness for younger infants with HSCR is debatable, robotic surgery could be successfully utilized for other diseases in the neonatal period [2,52]. We have gained experience in robotic surgery for these disorders and successfully applied robotic surgery for neonates and infants with HSCR. As younger infants have a narrower pelvis and more compact structures than older children, the distance between the rectum and the surrounding structures is smaller. Moreover, younger age is associated with more fragile tissue that is vulnerable to operative injury [53]. These features increase the risk of injuring perirectal neurovascular tissues and sphincters during laparoscopic procedures, but the robotic system supplies a stable magnified 3D surgical field and precise rectal dissection to avoid the risk of disruption to the perirectal tissues. We found that HSCR patients in the younger group (aged ≤ 3 mo) and older group (aged > 3

mo) exhibited comparable complication rates, BFS and POFC scores. These data demonstrated that SNS-RAPS is feasible for HSCR patients aged ≤ 3 mo, and its efficacy was comparable to that in the older group. This also indicated that SNS-RAPS has better efficacy than previously reported open and laparoscopic procedures when considered from another perspective. Although totally transanal surgery was an option for 22.73% of patients with lower rectum aganglionosis in this study, our RAPS could reduce the time and intensity of sphincter traction and provide better outcomes. Taken together, our findings further support the view that the protection afforded by RAPS to the anal sphincter and perirectal nerves is no worse than other approaches and that RAPS is a preferred option for HSCR.

Although our study demonstrated favorable outcomes for RAPS, the limitations include only short- to medium-term outcomes and the absence of comparative data with other approaches. Therefore, a long-term follow-up and comparative trial should be performed to evaluate the effect of SNS-RAPS on HSCR. Currently, assessing long-term outcomes is not an option because SNS-RAPS has been used for less than 10 years. We intend to perform this clinical trial in the next several years. Moreover, the currently documented drawbacks of robotic surgery are longer operative time, expensive costs and oversized robotic devices for infants and neonates, creating economic and technical constraints. With the further advancement of pediatric robot devices, the reduction in surgical costs, and the improvement in surgeons' skills, the application of robots in pediatric surgery will mature. If surgery is to provide less pain and more effective therapy, then minimally invasive procedures achieved *via* robots that share the advantages of open or laparoscopic procedures may offer the answer.

CONCLUSION

SNS-RAPS is a safe and effective option for children of all ages with HSCR. The robotic platform can be utilized to further minimize surgical damage to the perirectal neurovascular tissue and anal sphincter, contributing to better bowel and urination function.

ARTICLE HIGHLIGHTS

Research background

Robotic-assisted surgery has been gradually introduced and applied to treat children with Hirschsprung's disease (HSCR). However, few studies have been conducted to evaluate its safety and efficacy for HSCR treatment.

Research motivation

We aimed to investigate the medium-term outcomes of robotic-assisted surgery for treating HSCR.

Research objectives

We aimed to analyze the feasibility and efficacy of robotic-assisted proctosigmoidectomy (RAPS) with sphincter- and nerve-sparing surgery (SNS) in the treatment of HSCR.

Research methods

We conducted a multicenter prospective study of 156 infants with rectosigmoid HSCR who underwent SNS-RAPS and divided them by age into a younger group (aged ≤ 3 mo) and an older group (aged >3 mo) for comparison. Intraoperative data, postoperative complications, and medium-term outcomes were recorded and analyzed. In patients aged ≥ 4 years, the bowel function score (BFS) was used to assess overall bowel function, and the postoperative fecal continence (POFC) score was used to evaluate SNS-related incontinence.

Research results

A total of 156 patients underwent successful SNS-RAPS, with 25 complications within 30 days and 48 post-30-day complications after surgery. For children aged ≥ 4 years, the overall BFS was 17.32 ± 2.63 and 90.91% of patients showed moderate-to-good bowel

function, while the POFC score increased annually from 4 to 6 years old (4 years old: 10.95 ± 1.04 , 5 years old: 11.48 ± 0.72 , 6 years old: 11.94 ± 0.81). There were no significant differences between the younger and older groups in postoperative complications and POFC score.

Research conclusions

SNS-RAPS is a safe and effective alternative treatment in children of all ages with HSCR. It provides the advantage of further minimizing damage to sphincters and perirectal nerves, thus providing better continence function.

Research perspectives

Robotic-assisted surgery is beneficial for treating HSCR in infants and young children.

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